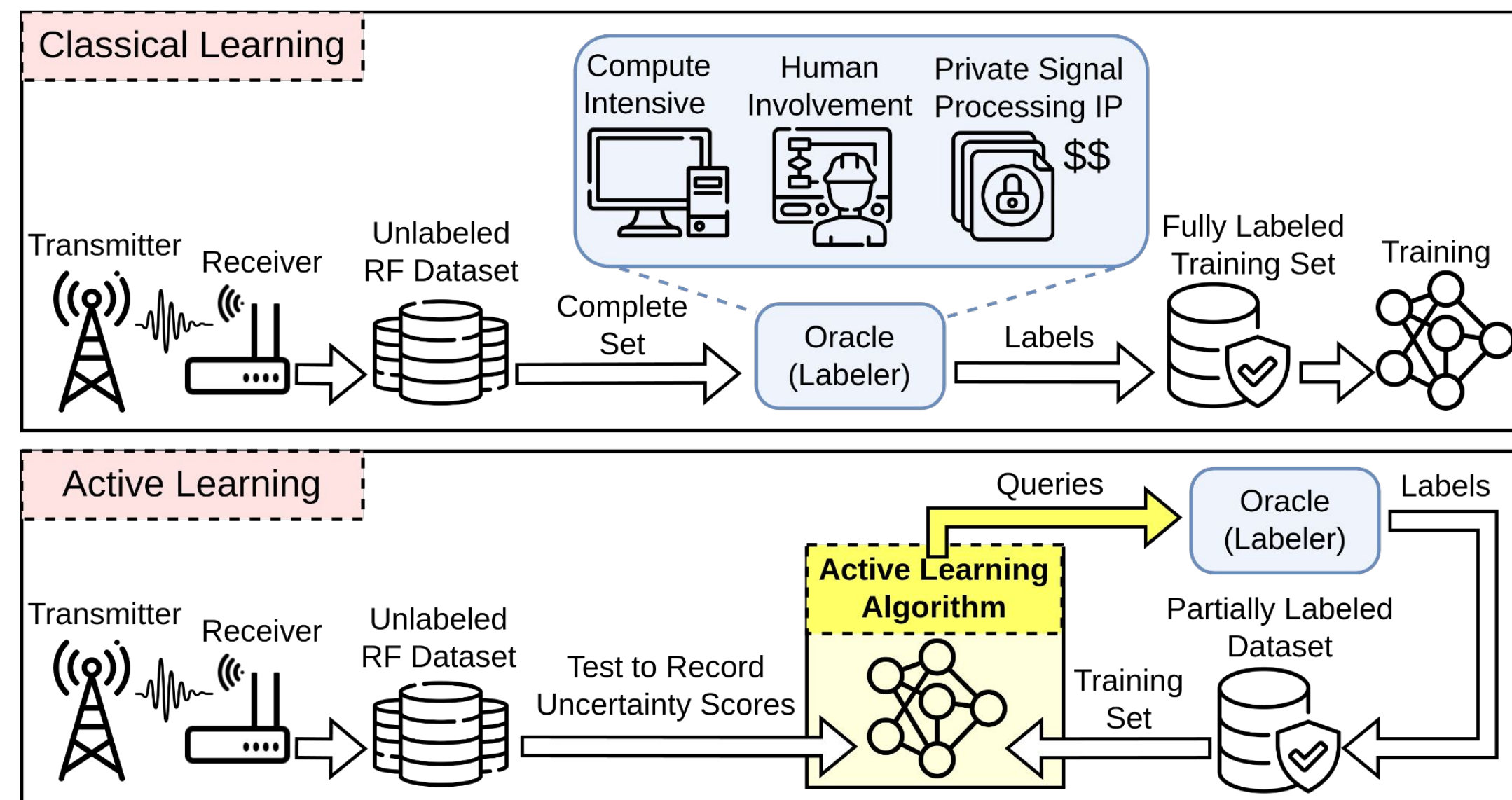
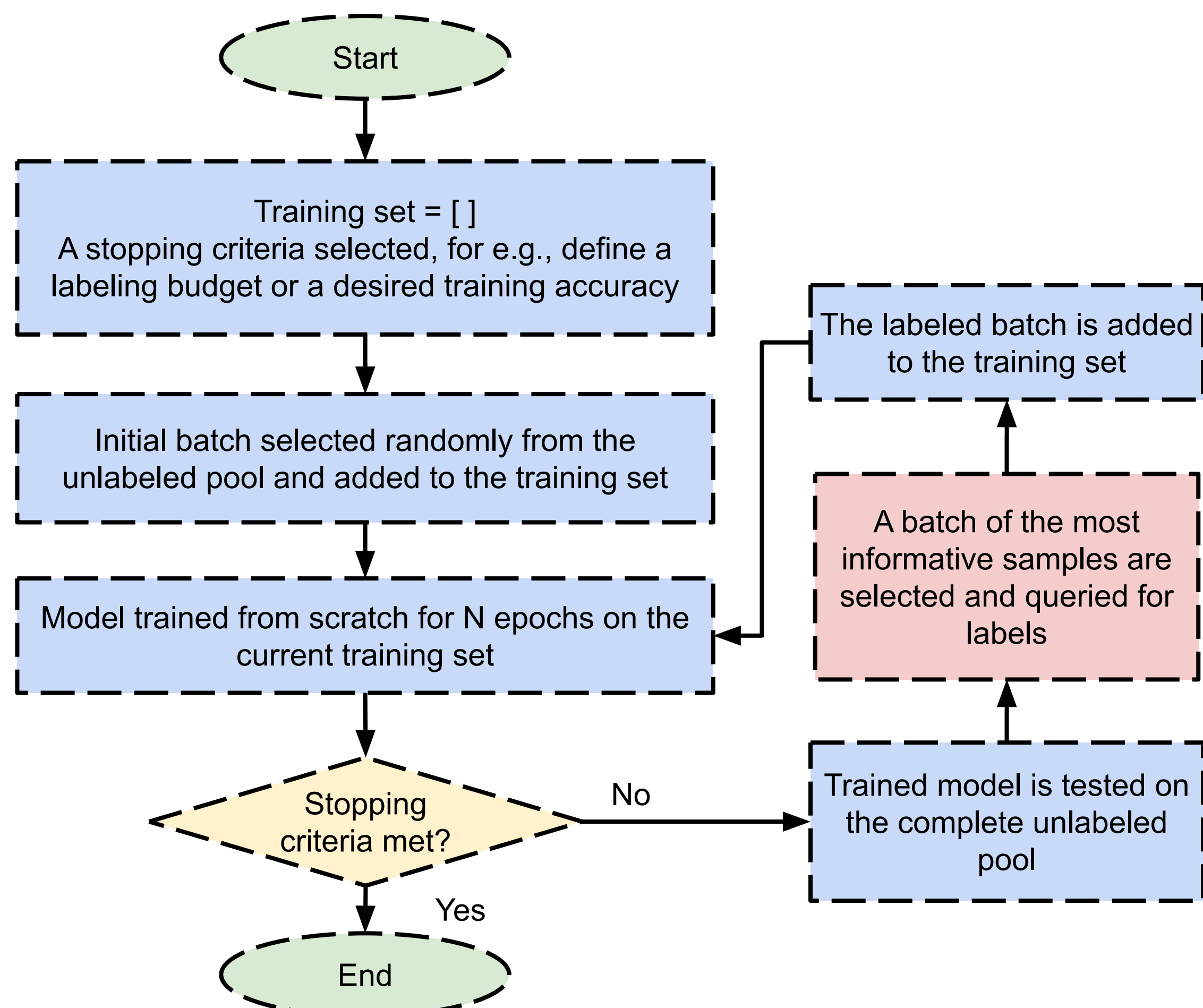


## Active Learning



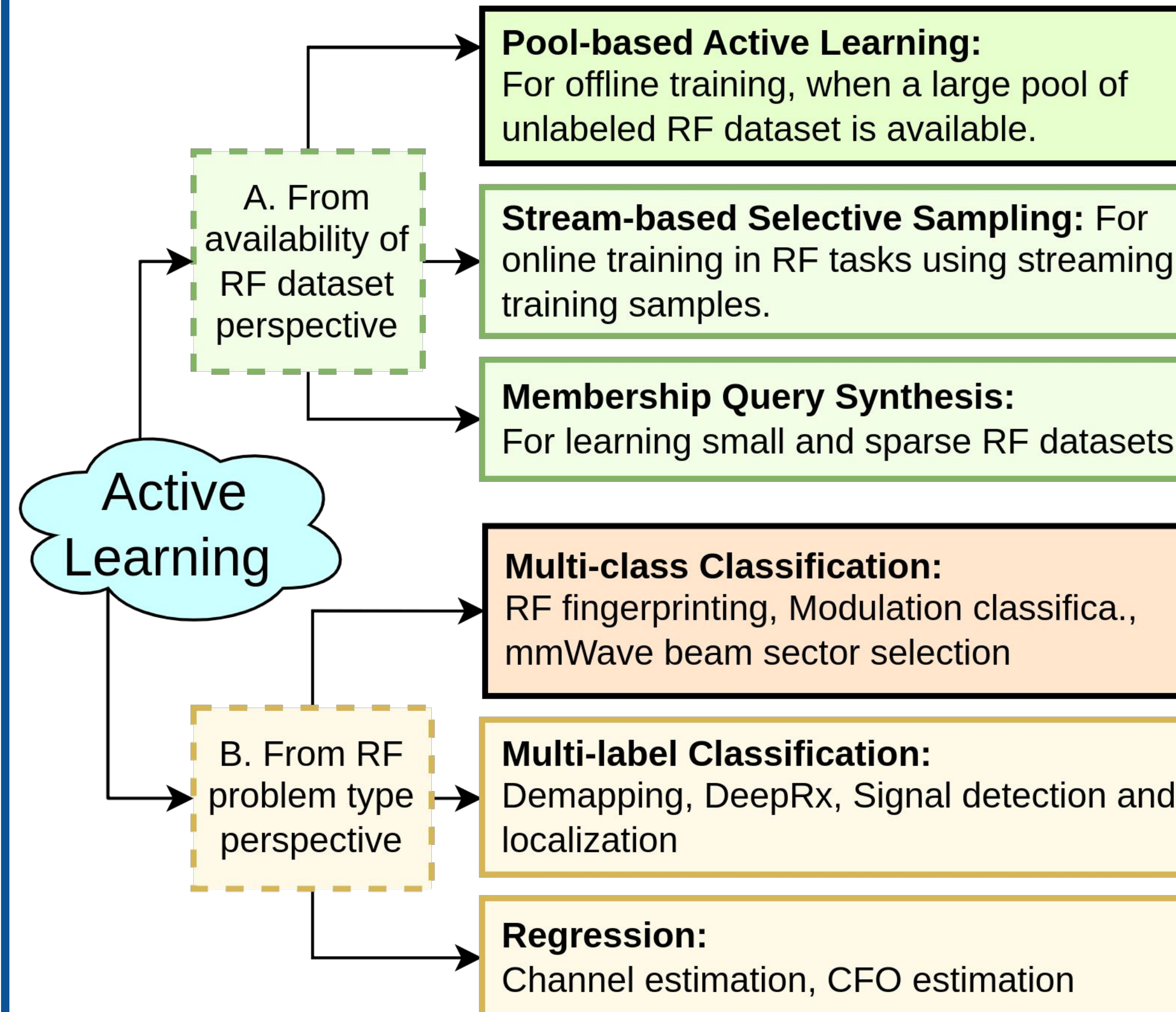
- We have unlimited labeling budget → Classical Learning
- We have a limited labeling budget → Active Learning

## Pool-based Active Learning

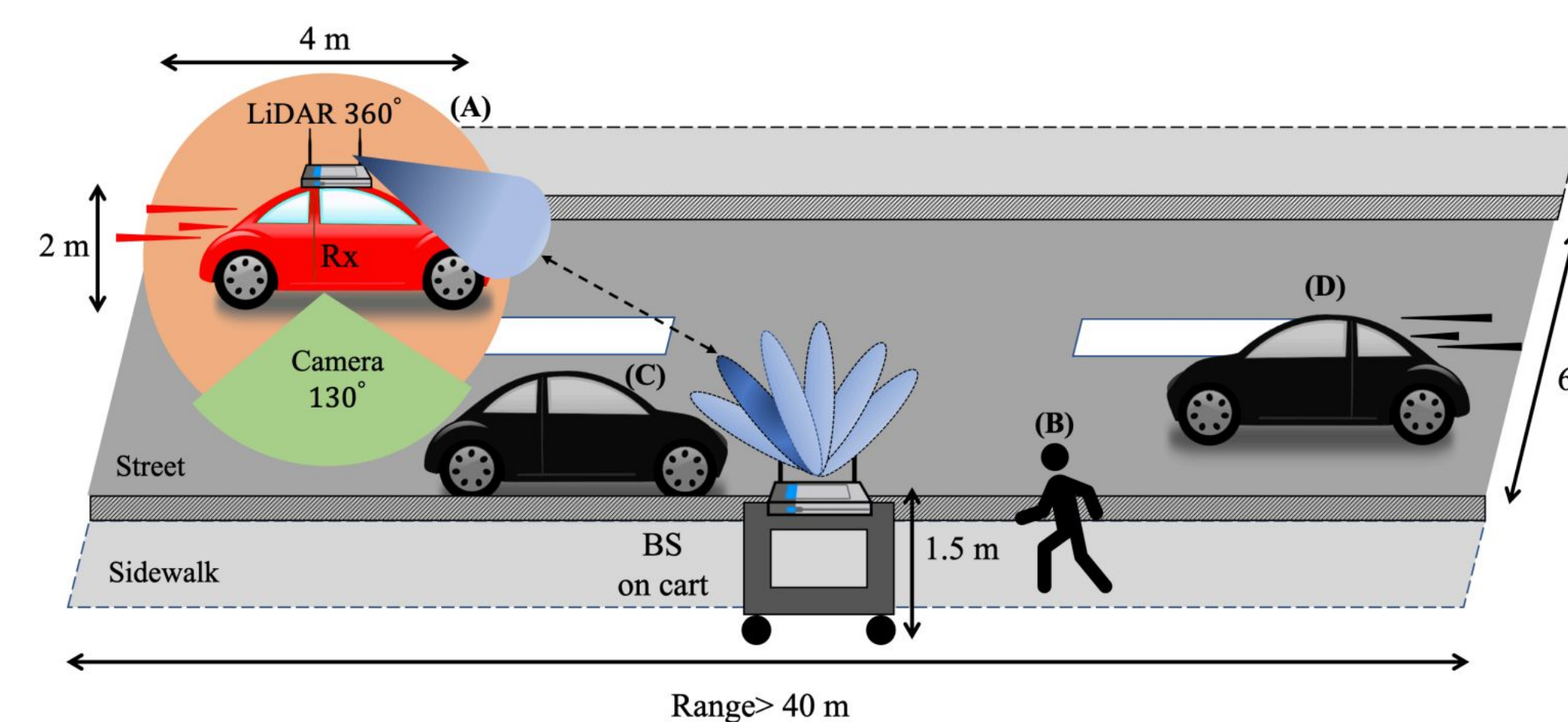


- Stopping Criteria: Iterative training stops when the training budget or desired accuracy is achieved.
- Informativeness Measure: Depends on the active learning algorithm.

## Active Learning for Wireless Comms.

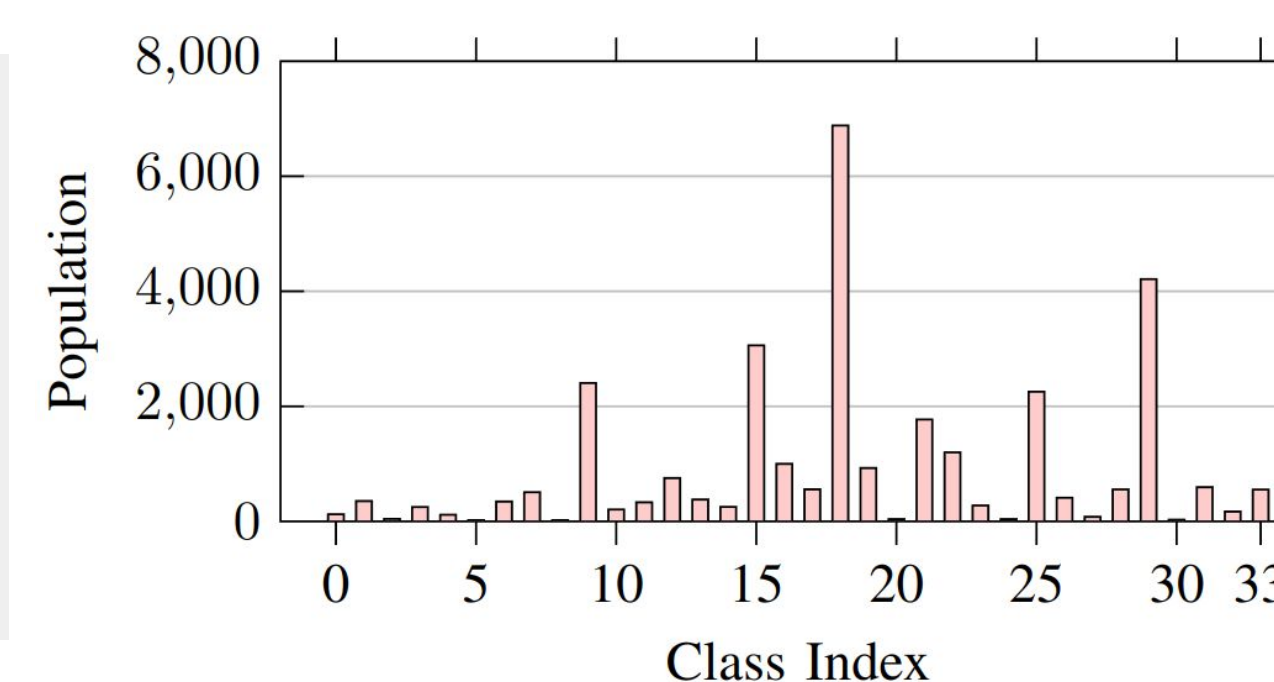


## mmWave Beam Sector Selection



- FLASH Dataset: Multi-modal (image, LiDAR, GPS) dataset collected from an autonomous car, while driving.

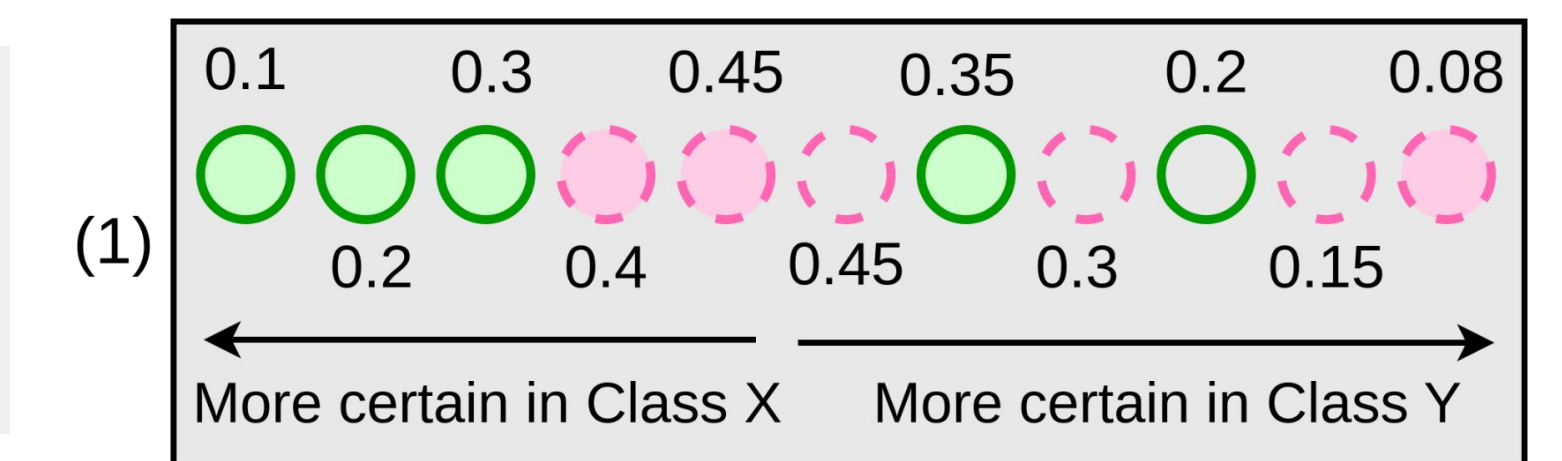
- The dataset has 34 classes (distinct beam indexes) and is extremely class imbalanced.



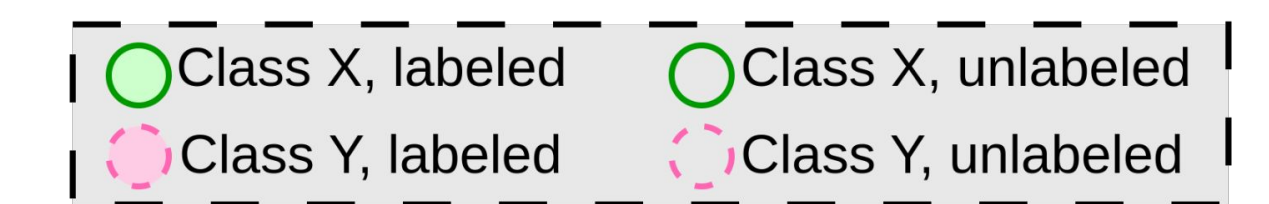
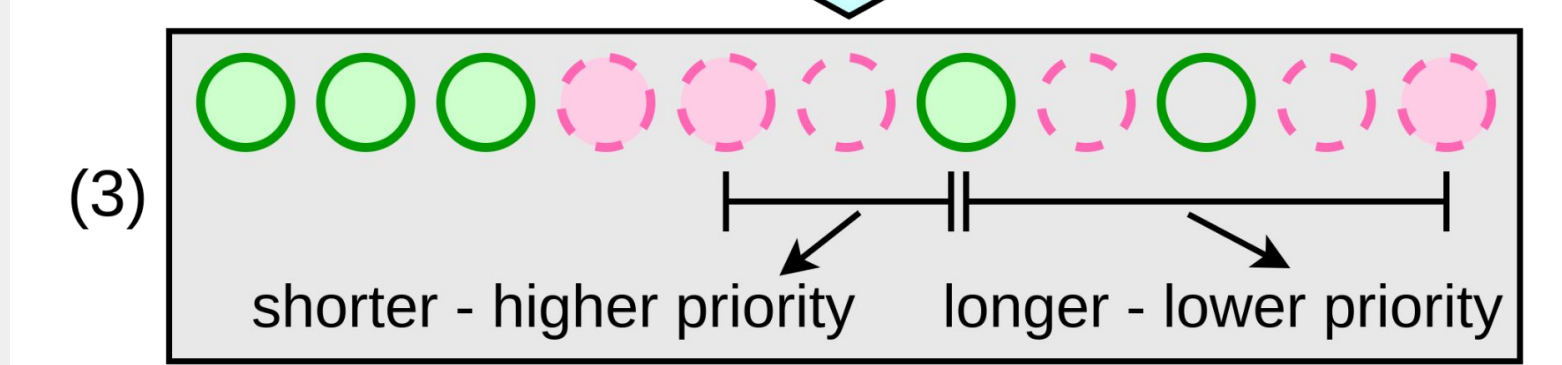
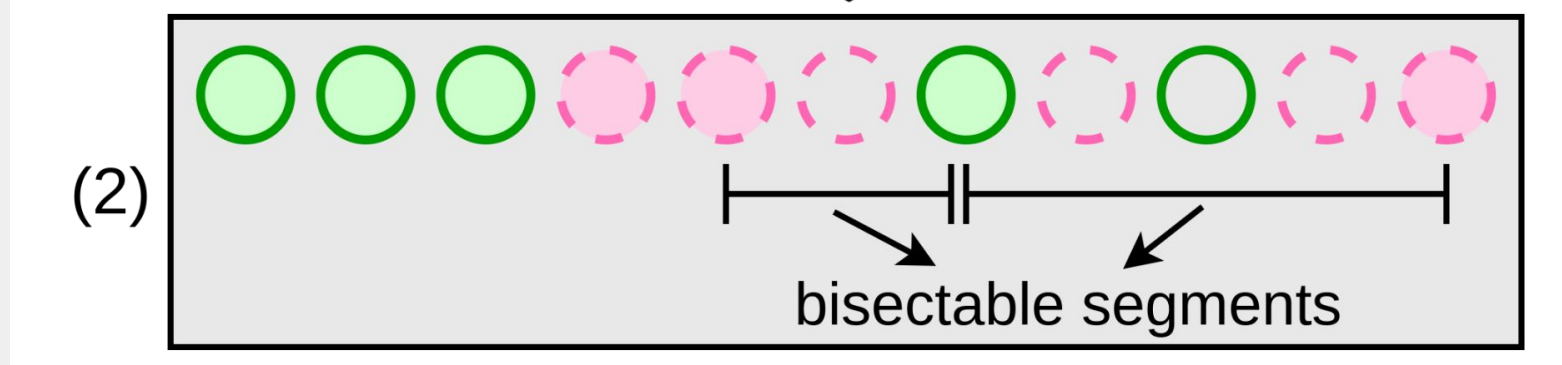
## GALAXY for Imbalanced Datasets

- (1) Uncertainty scores are calculated and the graphs are composed with sorted uncertainty scores for each class X versus all other classes as class Y.

- (2) Bisectable segments are identified.

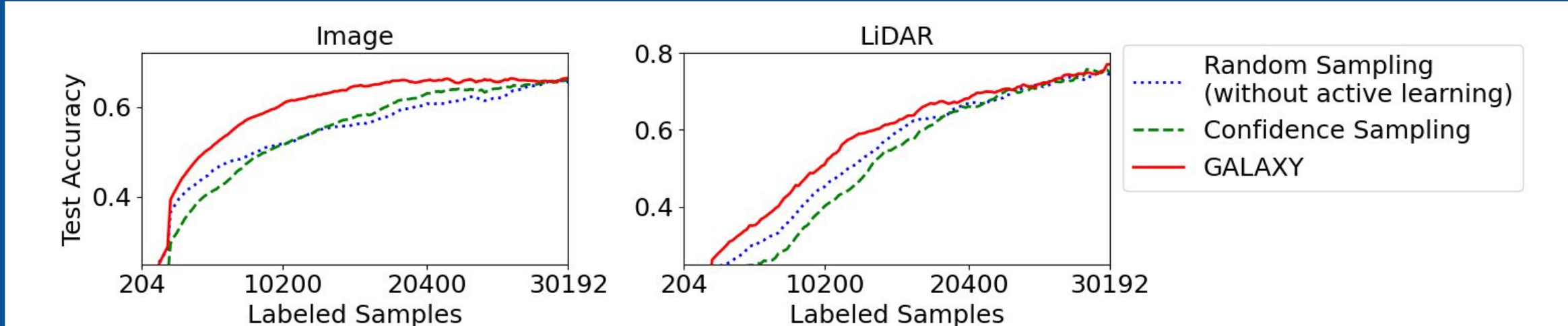


- (3) Bisectable segments are prioritized and the samples around all identified cuts in the bisectable segments are queried based on the priority.



- Cuts: edges that have nodes classified as different classes of X and Y.
- Bisectable segment: segment of consecutive nodes if its two ends are labeled as X and Y, and it contains no labeled cuts.

## Evaluation



**Image:** GALAXY reaches acc. 60% with 50% and 40% fewer labels compared to random and confidence sampling.

**LiDAR:** GALAXY reaches acc. 71% with 11% and 10% fewer labels compared to random and confidence sampling.

